

$$8. \underline{F} = \langle P(x,y,z), Q(x,y,z), R(x,y,z) \rangle$$

$$\text{curl}(\underline{F}) = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$= \underline{i} \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) - \underline{j} \left( \frac{\partial R}{\partial x} - \frac{\partial P}{\partial z} \right) + \underline{k} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$$

$$= \langle R_y - Q_z, P_z - R_x, Q_x - P_y \rangle$$

$$\begin{aligned} \text{div}(\text{curl}(\underline{F})) &= \frac{\partial}{\partial x} (R_y - Q_z) + \frac{\partial}{\partial y} (P_z - R_x) + \frac{\partial}{\partial z} (Q_x - P_y) \\ &= R_{yx} - Q_{zx} + P_{zy} - R_{xy} + Q_{xz} - P_{yz} \end{aligned}$$

By CLAIRAUT'S THM,  $R_{yx} = R_{xy}$ ,  $Q_{xz} = Q_{zx}$ ,  $P_{zy} = P_{yz}$  so

$$\begin{aligned} \text{div}(\text{curl}(\underline{F})) &= R_{yx} - R_{yx} + Q_{xz} - Q_{xz} + P_{zy} - P_{zy} \\ &= 0 \end{aligned}$$