

#11 (a) $f(x) = (x-1)(\sin x - \cos x) = 0$, then we obtain
the fixed points are $x^* = 1, x_k^* = \frac{\pi}{4} + k\pi, k=0, \pm 1, \dots$

$$\text{Here, } f'(x) = (\sin x - \cos x) + (x-1)(\cos x + \sin x) \\ = (x-2)\cos x + x\sin x$$

① $f'(x^*) = f'(1) = \sin 1 - \cos 1 > 0$, so $x^* = 1$ is linearly unstable.

$$② f'(x_k^*) = (-1)^k \sqrt{2} \left(\frac{\pi}{4} + k\pi \right)$$

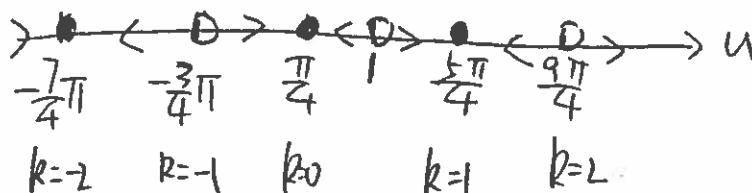
When $k < 0$, we have $f'(x_k^*) > 0, k = 2n+1, n=-1, -2, \dots$

and $f'(x_k^*) < 0, k = 2n, n=-1, -2, \dots$

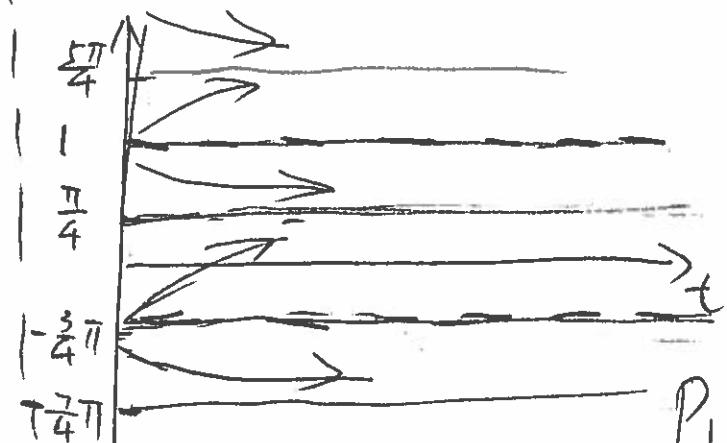
When $k \geq 0$, we have $f'(\frac{\pi}{4}) = \sqrt{2} \cdot \left(\frac{\pi}{4} \right) < 0$,

$f'(x_k^*) > 0, k = 2n, n=1, 2, \dots$ and $f'(x_k^*) < 0, k = 2n-1, n=1, 2, \dots$

Thus, the phase portrait is



; the graph of $x(t) - t$ is



$$(b). f(x) = (x^2 - 7x + 6)(6-x) = 0 \Rightarrow$$

$$x_1^* = 1 \text{ and } x_2^* = 6$$

Here, $f'(x) = (2x-7)(6-x) - (x^2 - 7x + 6) = -3x^2 + 26x - 48$

$$\textcircled{1} \quad f'(x_1^*) = f'(1) = -3 + 26 - 48 = -25 < 0$$

So $x_1^* = 1$ is linearly stable.

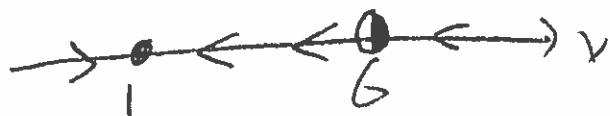
$$\textcircled{2} \quad f'(x_2^*) = f'(6) = 0, \text{ linear stability analysis fails.}$$

But using a graphical argument, we obtain

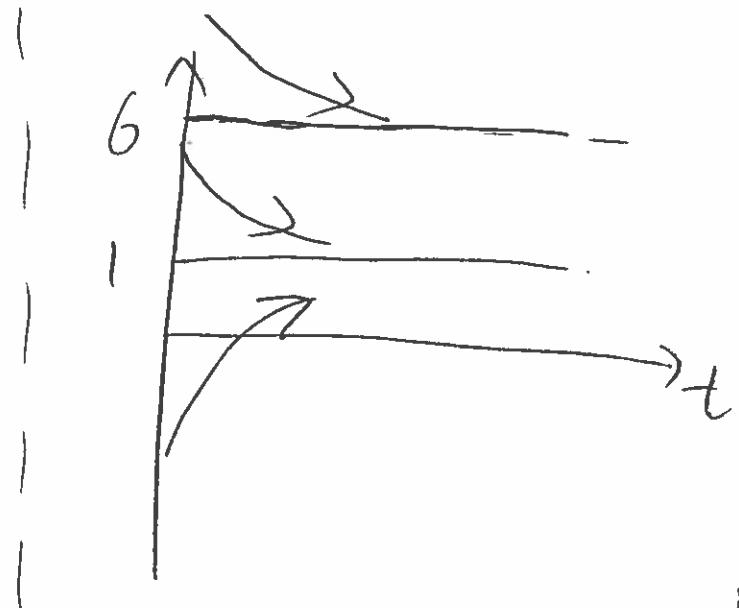


so $x_2^* = 6$ is half stable
and half unstable.

The phase portrait is

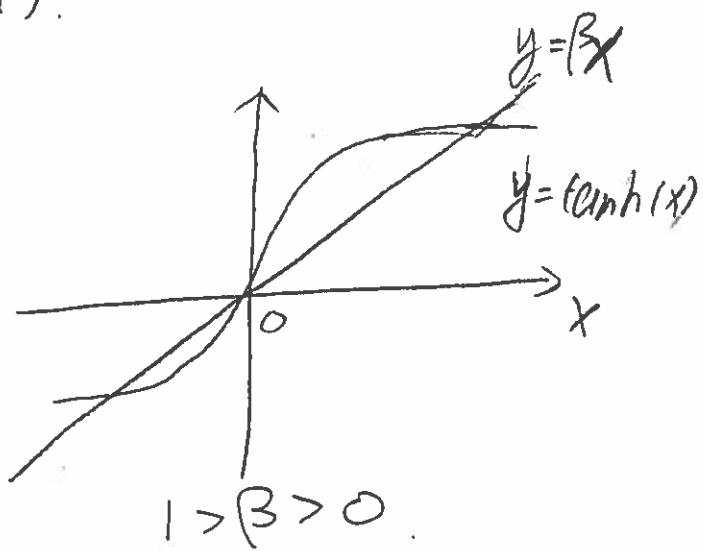
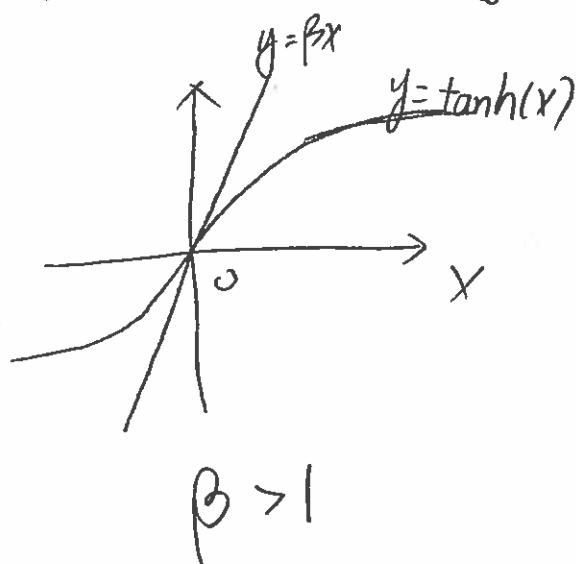


The graph of $x(t) - t$ is



(C) $f(x) = \tanh(x) - \beta x = 0$, i.e., $\tanh(x) = \beta x$, $\beta > 0$.

The fixed points are intersections of the line $y = \frac{\beta x}{\beta_0}$ and the curve $y = \tanh(x)$.



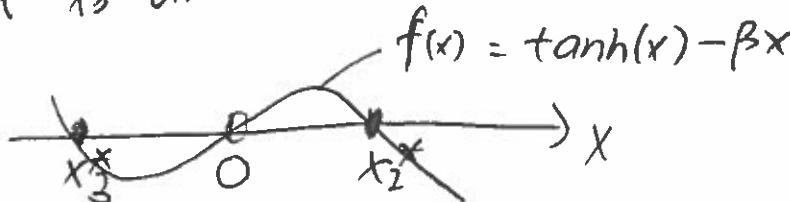
Thus, $\beta > 1$, only one fixed point $x^* = 0$.

$0 < \beta < 1$, three fixed points, $x_1^* = 0, x_2^* > 0, x_3^* < 0$

By linear stability analysis, we have $f'(x) = \operatorname{sech}^2(x) - \beta$.

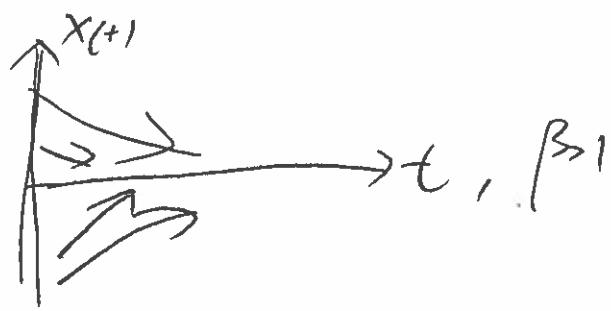
① $f'(0) = 1 - \beta$. So, $x_1^* = 0$ is linearly unstable when $0 < \beta < 1$, but stable when $\beta > 1$.

② With the help of graphical argument, we say x_1^* and x_3^* are stable but $x_1^* = 0$ is unstable. $0 < \beta < 1$

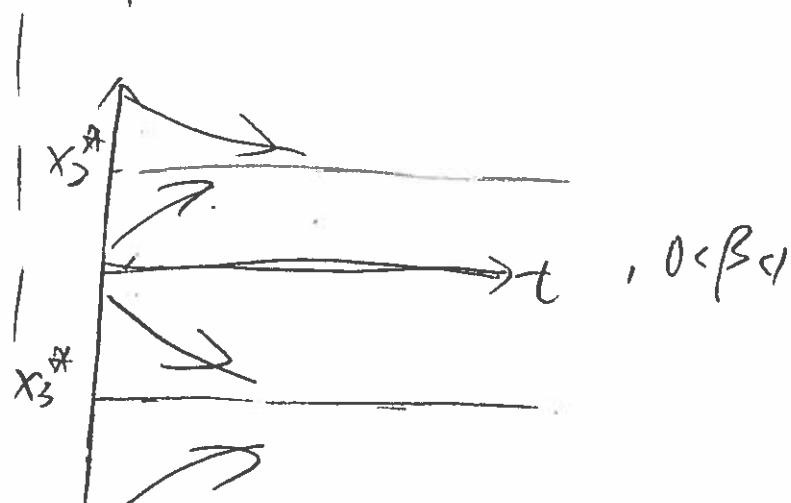
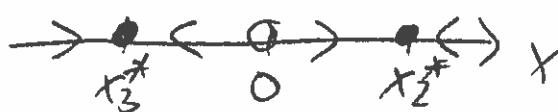


Thus the phase portrait is

$$\beta > 1$$



$$0 < \beta < 1$$



(1) $f(x) = Mx + x^3 - x^5 = 0, M > 0, \Rightarrow$

$$x_1^* = 0, x_2^* = \sqrt{\frac{1 + \sqrt{1 + 4M}}{2}}, x_3^* = -\sqrt{\frac{1 + \sqrt{1 + 4M}}{2}}$$

$f'(x) = M + 3x^2 - 5x^4$. So, for the stability, we have

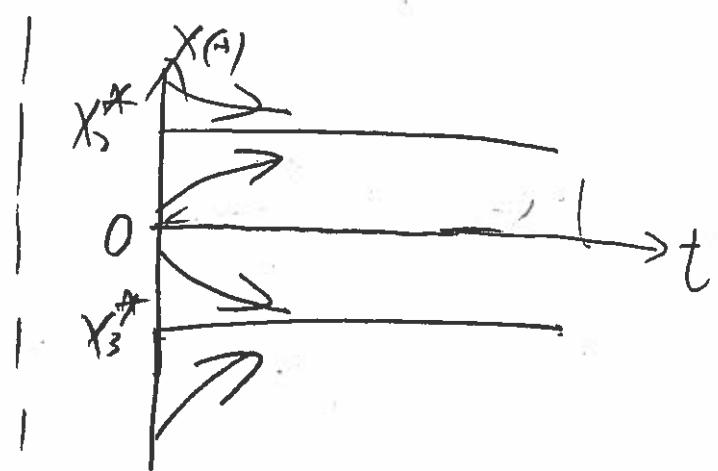
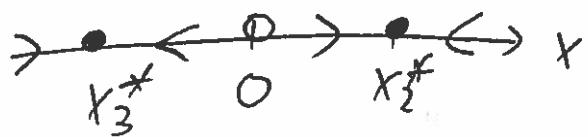
① $f'(x_1^*) = f'(0) = M > 0$, so $x_1^* = 0$ is linearly unstable.

② $f'(x_2^*) = M + 3(x_2^*)^2 - 5(x_2^*)^4 = -2(x_2^*)^2 - 4M < 0$

③ $f'(x_3^*) = -2(x_3^*)^2 - 4M < 0$

So, x_2^* , x_3^* are stable

Thus, the phase portrait is



$$\# 2.(a) f(x) = x(1 - rx + x^2) \Rightarrow x_1^* = 0,$$

If $r^2 < 4$, i.e., $-2 < r < 2$, there is only one fixed point $x_1^* = 0$

If $r^2 = 4$, i.e., $r = \pm 2$, there are two fixed points:

$$x_1^* = 0, \quad x_2^* = 1, \text{ when } r=2 \quad (\text{OR}) \quad x_1^* = 0, \quad x_2^* = -1, \quad \text{when } r=-2.$$

If $r^2 > 4$, i.e., $r > 2$ or $r < -2$, there are three fixed points

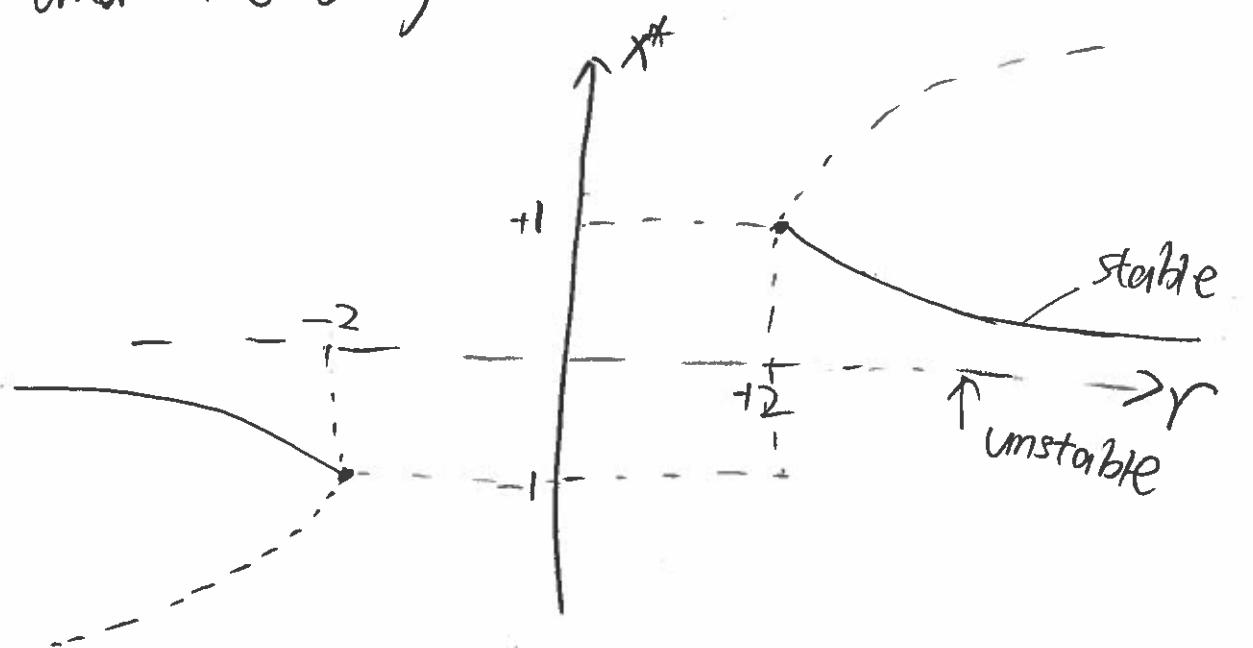
$$x_1^* = 0, \quad x_2^* = \frac{r + \sqrt{r^2 - 4}}{2} \quad \text{and} \quad x_3^* = \frac{r - \sqrt{r^2 - 4}}{2}.$$

As for the stability, we have $f'(x) = 1 - 2rx + 3x^2$

$$f'(x_1^*) = 1; \quad f'(x_2^*) = \frac{r + \sqrt{r^2 - 4}}{2} \cdot \sqrt{r^2 - 4} \begin{cases} > 0 & (r > 2) \\ < 0 & (r < -2) \end{cases}$$

$$f'(x_3^*) = \frac{r - \sqrt{r^2 - 4}}{2} \cdot (-\sqrt{r^2 - 4}) \begin{cases} < 0 & (r > 2) \\ > 0 & (r < -2) \end{cases}$$

Thus, a saddle-node bifurcation occurs at $r_c = \pm 2$
and the diagram is:



$$(b) f(x) = (x-1)(r - e^{-x}) = 0 \Rightarrow$$

- If $r \leq 0$, there is only one fixed point $x^* = 1$.

- If $0 < r < e^{-1}$, there are two: $x_1^* = 1, x_2^* = -\ln r$

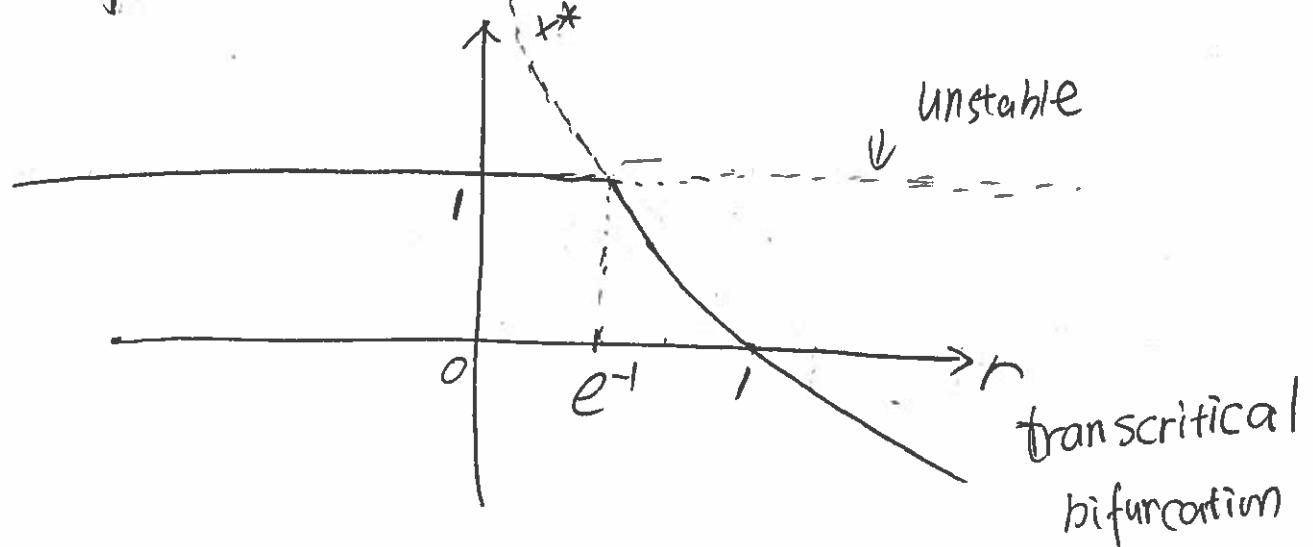
- If $r = e^{-1}$, there is only one: $x_1^* = 1$

- If $r > e^{-1}$, there are two: $x_1^* = 1, x_2^* = -\ln r$

As for the stability, we have $f'(x) = r - 2e^{-x} + xe^{-x}$

$$f'(1) = r - e^{-1} = \begin{cases} > 0, & r > e^{-1} \\ = 0, & r = e^{-1} \\ < 0, & r < e^{-1} \end{cases}, \quad f'(-\ln r) = r \cdot \left(\ln \frac{1}{r}\right) = \begin{cases} > 0, & 0 < r < e^{-1} \\ = 0, & r = e^{-1} \\ < 0, & r > e^{-1} \end{cases}$$

Thus, a bifurcation occurs at $r_c = e^{-1}$, and the diagram is



$$(C) f(x) = rx - \frac{x}{1+x^2} = 0 \Rightarrow$$

If $r \leq 0$, there is only one fixed point: $x^* = 0$.

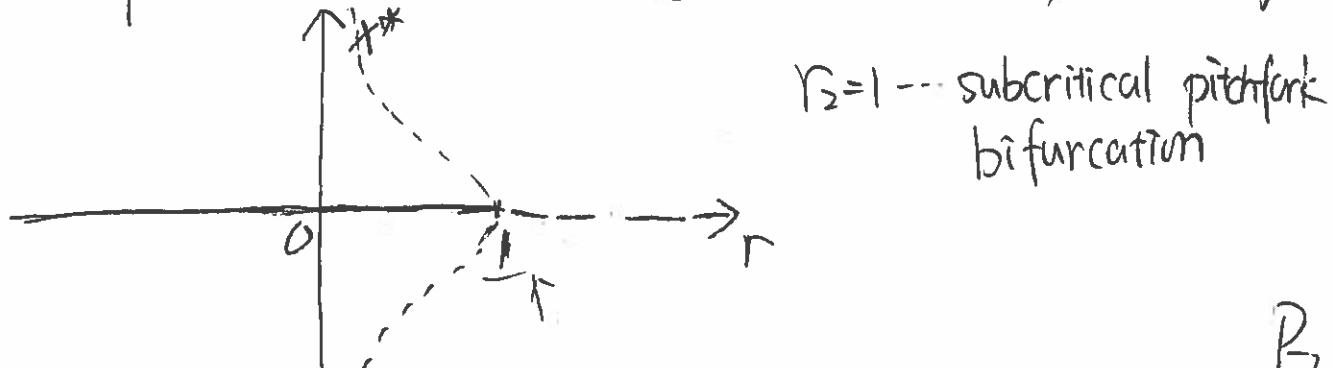
If $0 < r < 1$, there are three: $x_1^* = 0$, $x_2^* = \sqrt{\frac{1-r}{r}}$, $x_3^* = -\sqrt{\frac{1-r}{r}}$.

If $r \geq 1$, there is only one: $x_1^* = 0$.

As for the stability, we have $f'(x) = r - \frac{1}{1+x^2} + \frac{2x^2}{(1+x^2)^2}$.

$$f'(0) = r-1, \quad f'(x_2^*) = 2r(1-r) > 0, \quad f'(x_3^*) = 2r(1-r) > 0$$

Thus, the bifurcation occurs at ~~$r_c = 1$~~ $r_c = 1$, the diagram is



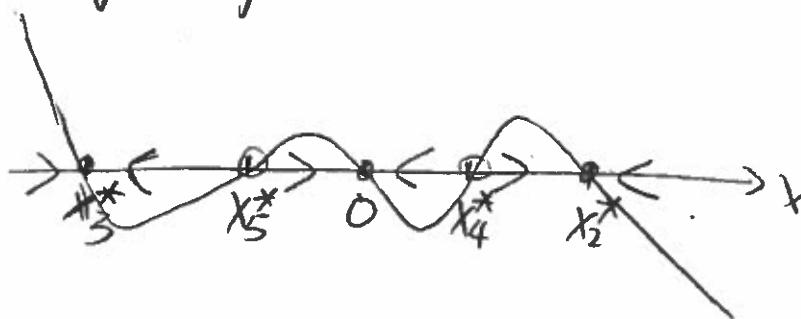
(d) $f(x) = rx + x^3 - x^5 = 0$. As we did in 1(d), when $r \geq 0$, there are three fixed points: $x_1^* = 0$ unstable, $x_2^* = \sqrt{\frac{1+\sqrt{1+4r}}{2}}$ stable and $x_3^* = -\sqrt{\frac{1+\sqrt{1+4r}}{2}}$ stable.

Now, let's consider the case where $r < 0$.

If $-\frac{1}{4} < r < 0$, there are five fixed points:

$$x_1^* = 0, x_2^* = \sqrt{\frac{1+\sqrt{1+4r}}{2}}, x_3^* = -\sqrt{\frac{1+\sqrt{1+4r}}{2}}, x_4^* = \sqrt{\frac{1-\sqrt{1+4r}}{2}}, x_5^* = -\sqrt{\frac{1-\sqrt{1+4r}}{2}}$$

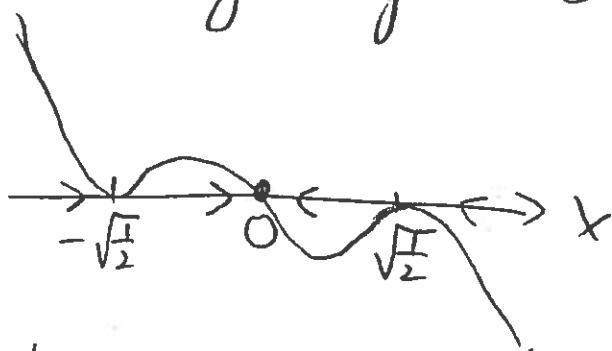
By linear stability analysis, we obtain the phase portrait as



If $r = -\frac{1}{4}$, there are three fixed points:

$$x_1^* = 0, x_2^* = \sqrt{\frac{1}{2}}, x_3^* = -\sqrt{\frac{1}{2}}$$

By linear stability analysis, we obtain the phase portrait as



which is stable

If $r < -\frac{1}{4}$, there is only one fixed point $x^* = 0$, ✓

~~unstable~~ stable

Thus, a saddle-node bifurcation occurs at $r_1 = -\frac{1}{4}$, and a supercritical pitchfork bifurcation occurs at $r_2 = 0$.

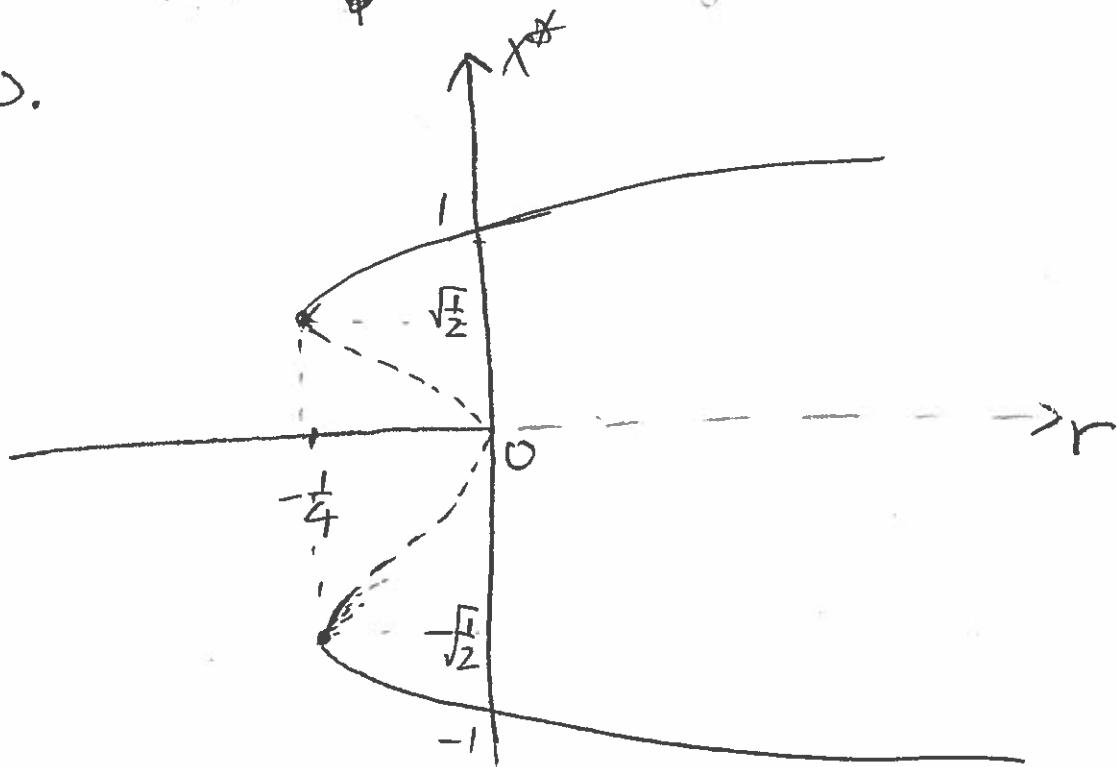


Fig 12.