

## MATH 2051 MIDTERM EXAM on February 22,2008 Answers

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**Student:**

1. (9 points)

(a) Complete the definition:

*A linear (vector) space is a collection of vectors with the following properties:*

(1) it contains the zero vector  $\vec{0}$  — such that for any vector  $\vec{v}$  from the collection  $\vec{0} + \vec{v} = \vec{v} + \vec{0} = \vec{v}$ ;

(2) the sum of any two vectors from the collection is again in the collection;

(3) a multiple of any vector from the collection is again in the collection.

(b) Use you definition in part (a) to prove that:

*The collection of all vectors  $\vec{v} = (x, y, z)^T$  which are orthogonal to vector*

$$\vec{n} = (22, 2, 2008)^T$$

*form a linear (vector) space.*

Solution: Note that the collection include all  $\vec{v} = (x, y, z)^T$  such that

$$22x + 2y + 2008z = 0.$$

Now we will check all three properties.

(1)  $\vec{0} = (0, 0, 0)^t$  belongs to the collection because substitution of  $x = y = z = 0$  into the equation above gives a true statement  $0=0$ .

(2) Let  $\vec{v}_1 = (x_1, y_1, z_1)^T$  such that  $22x_1 + 2y_1 + 2008z_1 = 0$  and  $\vec{v}_2 = (x_2, y_2, z_2)^T$  such that  $22x_2 + 2y_2 + 2008z_2 = 0$ , that is both vectors are from the collection. By adding these two equations we obtain  $22(x_1 + x_2) + 2(y_1 + y_2) + 2008(z_1 + z_2) = 0$ .

Thus the sum of the vectors

$$\vec{v}_1 + \vec{v}_2 = (x_1 + x_2, y_1 + y_2, z_1 + z_2)^T$$

also belongs to the collection.

(3) Let  $\vec{v}_1 = (x_1, y_1, z_1)^T$  such that  $22x_1 + 2y_1 + 2008z_1 = 0$ . Multiplying this equation by any number  $k \neq 0$  we get  $22kx_1 + 2ky_1 + 2008kz_1 = 0$ , thus vector  $k\vec{v}_1 = (kx_1, ky_1, kz_1)^T$  also belongs to the collection.

All three properties are verified, thus this collection of vectors is a vector space.

2. (9 point)

- (a) Give a definition of  $n$  **linearly independent** vectors.

Answer: None of the  $n$  vectors can be expressed as a linear combination of the rest  $n - 1$  vectors.

- (b) Let the columns of a rectangular  $m \times n$  matrix  $A$  be linearly independent vectors, and  $m \neq n$ . Which of the following are TRUE?

(1)  $m > n$

(2)  $m < n$

(3) linear independence of columns is possible only for  $m = n$ .

(4) system  $AX = B$  has a *unique* solution for *any*  $m \times 1$  matrix  $B$ .

(5) system  $AX = B$  has a *parametric* solution for *some*  $m \times 1$  matrices  $B$ .

(6) **system  $AX = B$  has a unique solution for some  $m \times 1$  matrices  $B$ .** Matrix  $B$  must be in the column space of  $A$ .

- (c) Give an example of a matrix with four linearly independent rows. What is the rank of your matrix?

Answer: Identity  $4 \times 4$  matrix is an example.

Rank is 4.

3. (8 point)

Let  $\vec{f}_1 = \vec{e}_1 + 2\vec{e}_2$ ,  $\vec{f}_2 = 3\vec{e}_1 + 4\vec{e}_2$ , and  $\vec{v} = 5\vec{e}_1 + 6\vec{e}_2$ ,

- (a) Find the matrix of coordinate transformation for the change from basis  $(\vec{e}_1, \vec{e}_2)$  to basis  $(\vec{f}_1, \vec{f}_2)$ ;

Answer:  $\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$

- (b) Find the matrix of coordinate transformation for the change from basis  $(\vec{f}_1, \vec{f}_2)$  to basis  $(\vec{e}_1, \vec{e}_2)$ ;

Answer:  $\begin{bmatrix} -2 & 1.5 \\ 1 & -0.5 \end{bmatrix}$

- (c) Find numbers  $a, b$  such that  $\vec{v} = a\vec{f}_1 + b\vec{f}_2$ .

Answer:  $a = -1, b = 2$

4. (9 points)

- (a) Give a definition of **basis** in a vector space.

Answer: Basis in a space is a collection of linearly independent vectors which span the space.

It has the property that every vector in the space can be represented as a linear combination of basis in a unique way.

- (b) Find a basis in the **column space** of matrix  $\begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 3 & 6 & 9 & 12 & 13 & 14 \end{bmatrix}$

Answer: basis in column space is  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 5 \\ 13 \end{bmatrix}$ .

- (c) Find a basis in the **eigenspace** of matrix  $\begin{bmatrix} 2008 & 2008 & 2008 \\ 0 & 2008 & 2008 \\ 0 & 0 & 2008 \end{bmatrix}$

Answer: Eigenvalue  $\lambda = 2008$  has multiplicity 3. The only eigenvector is  $X = (t, 0, 0)^T$ . Thus basis consists of only one vector  $(1, 0, 0)^T$ .

5. (14 points)

- (a) Let  $\vec{v}_1, \vec{v}_2, \vec{v}_3$  be an orthonormal basis in a vector space  $S$ . Let  $(x, y, z)$  denote coordinates of a vector  $\vec{w} \in S$  w.r.t this basis. Prove that

$$x = \vec{w} \cdot \vec{v}_1, \quad y = \vec{w} \cdot \vec{v}_2, \quad z = \vec{w} \cdot \vec{v}_3.$$

Answer: there are many ways to prove this statement. One possibility is as follows.

Let

$$\vec{w} = x\vec{v}_1 + y\vec{v}_2 + z\vec{v}_3.$$

Then

$$\vec{w} \cdot \vec{v}_1 = x\vec{v}_1 \cdot \vec{v}_1 + y\vec{v}_2 \cdot \vec{v}_1 + z\vec{v}_3 \cdot \vec{v}_1.$$

Since the basis is orthonormal we have  $\vec{v}_1 \cdot \vec{v}_1 = 1$ ,  $\vec{v}_2 \cdot \vec{v}_1 = 0$ ,  $\vec{v}_3 \cdot \vec{v}_1 = 0$ . Thus  $\vec{w} \cdot \vec{v}_1 = x$ . Similarly we find that  $\vec{w} \cdot \vec{v}_2 = y$  and  $\vec{w} \cdot \vec{v}_3 = z$ .

- (b) Show that the following set of vectors is an **orthogonal basis** in space  $S = \text{span}(\vec{f}_1, \vec{f}_2, \vec{f}_3)$

$$\vec{f}_1 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \quad \vec{f}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ -4 \end{bmatrix}, \quad \vec{f}_3 = \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix}.$$

Answer: Check directly that  $\vec{f}_1 \cdot \vec{f}_2 = 0$ ,  $\vec{f}_1 \cdot \vec{f}_3 = 0$ ,  $\vec{f}_2 \cdot \vec{f}_3 = 0$ .

Also the vectors are linearly independent. Thus they form an orthogonal basis in  $S$ .

- (c) Obtain **orthonormal basis** from vectors  $\vec{f}_1, \vec{f}_2, \vec{f}_3$  given in (b), by normalization. Call the vectors you found  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ .

Answer:

$$\vec{v}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \quad \vec{v}_2 = \frac{1}{3\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -4 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}.$$

(d) Find coordinates of  $\vec{w} = (4, 9, 4, -7)^T$  w.r.t the orthonormal basis  $\vec{v}_1, \vec{v}_2, \vec{v}_3$  found in (c).

Answer: Use statement from (a) to find

$$x = \vec{w} \cdot \vec{v}_1 = 3, \quad y = \vec{w} \cdot \vec{v}_2 = 6\sqrt{2}, \quad z = \vec{w} \cdot \vec{v}_3 = 9,$$